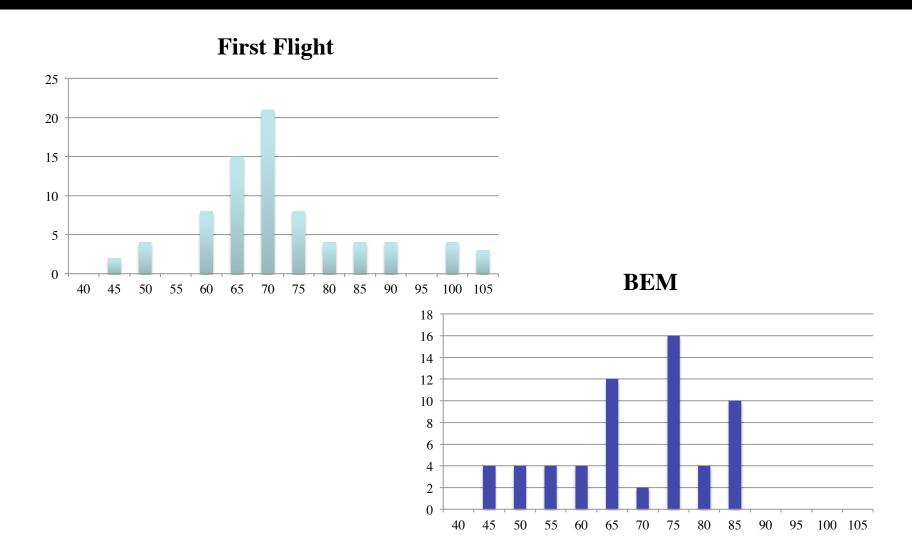
Experimental Engineering



Thrust and Flight Modeling Static Motor Tests and Flight Modeling Lab









<u>Outline</u>

- Static Motor Tests and Flight Modeling Lab Overview
- Flight Modeling:
 - 1 Degree of Freedom (DOF) Model
 - 3 DOF Model

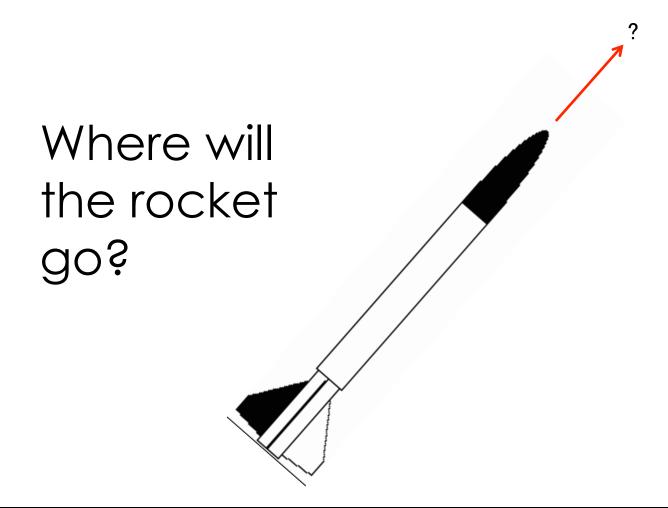


Static Motor Rotation Lab Objectives

- Measure the thrust curves, mass flow rate of combustion gases and specific impulse for two rocket motors.
- Construct analytical and 1-D (1 DOF) and 2-D (3 DOF) numerical models of rocket flight.
- Compare the analytical and numerical models with the output of RockSim or OpenRocket.











Flight modeling

What key forces dictate the flight trajectory?



Reminder: Lift and Drag

The sum of pressure and shear stress is the resultant force. It is split into two components:

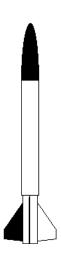
- Lift: The component of resultant force that is perpendicular to the incoming net velocity vector (effective flow direction).
- 2. **Drag:** The component of resultant force that is **parallel** to the incoming net velocity vector (effective flow direction).







One DOF Model: Free Body Diagram

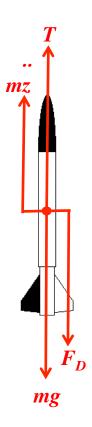






One DOF Model: Governing Equation

..

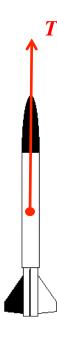


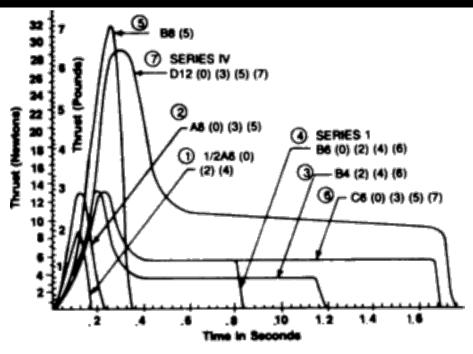




Modeling Thrust

Is thrust constant during flight?



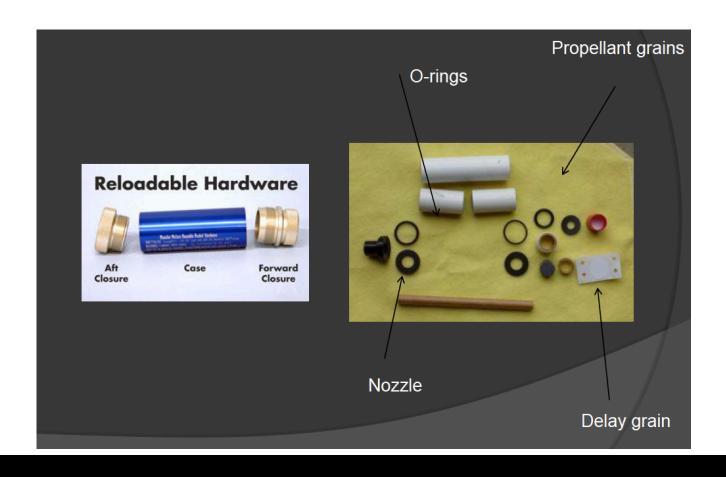


Engine Type	Total Impulse		Average Thrust			Thrust
	Pound- seconds	Newton seconds	Pounds	Newtons	Propellant Weight	Curve Number
1/2A6-	0.28	1.25	1.35	5.80	0.00344 b	1
A8-	0.56	2.50	1.80	7.70	0.00918 lb.	2
B4-	1.12	5.00	0.90	4.15	0.01836 lb.	3
B6-	1.12	5.00	1.35	5.80	0.01374 b .	4
B8-	1.12	5.00	1.79	8.00	0.01374 lb.	5
C6-	2.25	10.00	1 35	5.80	0.02748 lb.	6
D12-	4.48	20.00	2.66	11.80	0.05496 lb	7





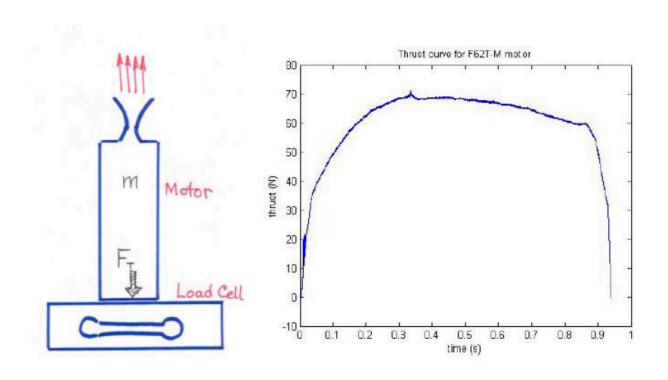
Static Motor Rotation Lab







Static Motor Thrust Curve



http://www.eng.hmc.edu/NewE80/StaticTestVideos.html





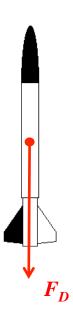
Static Motor Lab, Section 2:

- Calculate the total impulse.
- Calculate the average thrust and average mass flow rate.
- Calculate the exit velocity of the combustion gases from the nozzle. What assumptions did you have to make?
- Calculate the specific impulse, I_{sp}.





Drag Force







Analytical One DOF Model

• GE:

$$m\ddot{z} = T - mg - F_D$$

Assumptions:





Numerical One DOF Model

GE:

- · Many options for numerical solution methods, e.g.
 - OpenRocket uses Runge-Kutta (RK4)
 - One option is **Explicit Euler** ignoring high order terms...





Explicit Euler



One DOF Model

```
for t = 0 to maxTime 

{

T = ...

m = ...

Fd = ...

z_d(t) = 1/m^*(T-m^*g-Fd);

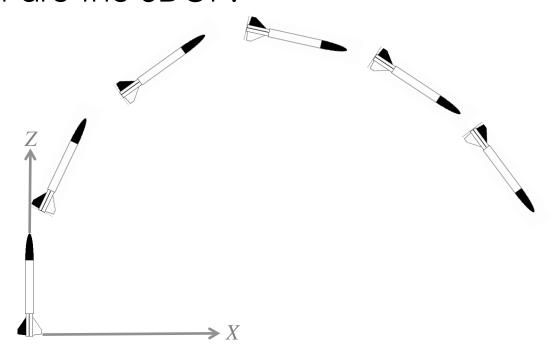
z_d(t) = z_d + z_dd^*\Delta t

z(t) = z + z_d^*\Delta t
}
```



Three DOF Model

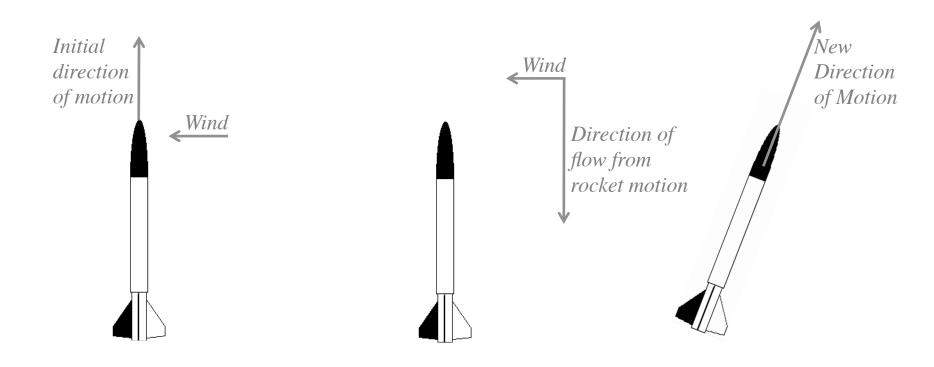
What are the 3DOF?







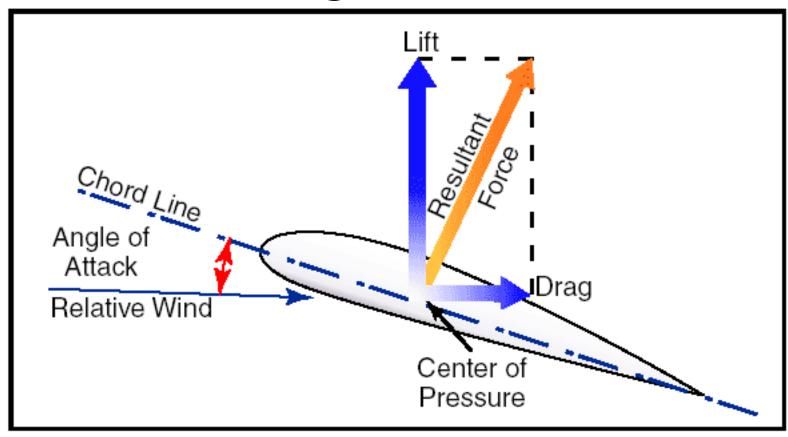
Why does the rocket rotate?







Reminder: Angle of Attack







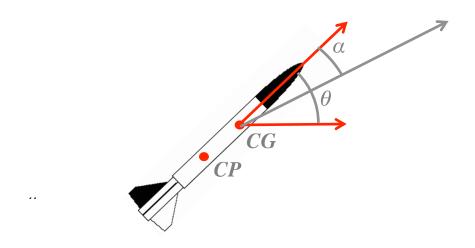
Angle of Attack

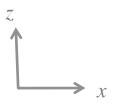






Three DOF Free Body Diagram





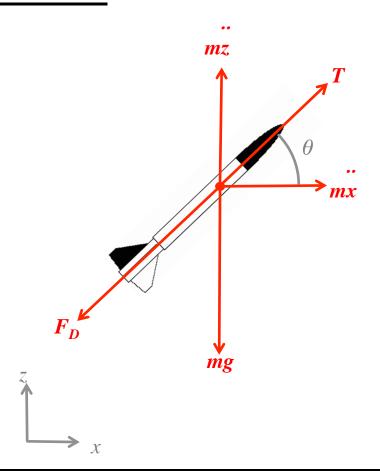




Non-Rotational Forces

z-direction

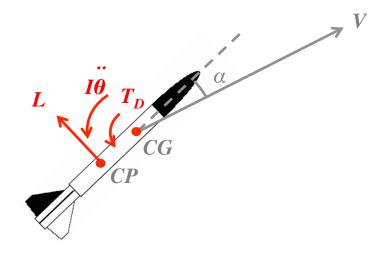
x-direction







Torque Balance







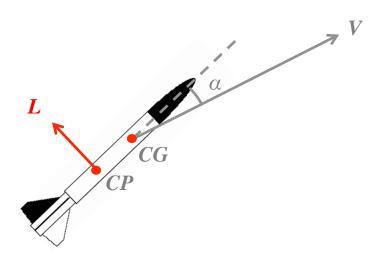
Rotational Damping

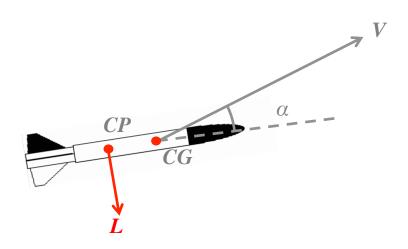
The rotational damping can be modeled as



Rocket Stability

- · Is this stable?
 - Depends on location of C_P versus C_G

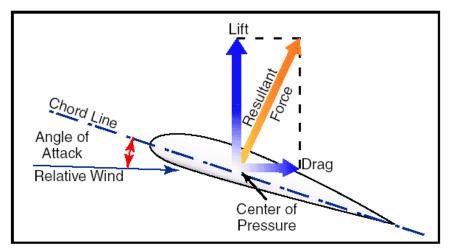








Reminder: Complication #3 Angle of Attack



$$C_L, C_D = f(\alpha, Re)$$

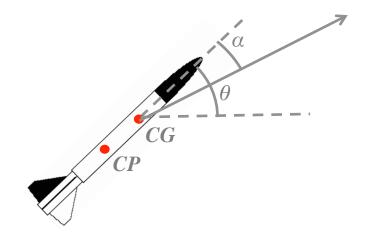




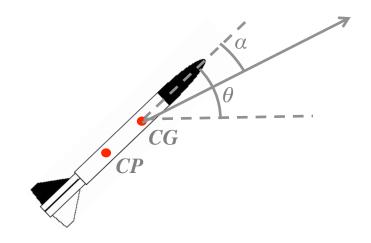
Drag and Lift direction

Drag and lift can be defined w.r.t.

Rocket axis



Effective flow direction





Three DOF Model

```
for t = 0 to maxTime
{
            T = ...
             m = \dots
             Fd = ...
             L = ...
             Td = \dots
             alpha = ...
             z_dd(t) = ...
             x_dd(t) = ...
             \theta_{dd}(t) = ...
```



To Linde Field

Good luck!

