

Current Mirrors

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E151 – Analog Circuit Design

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In this video series we're going to study a transistor structure that is used for biasing amplifiers and active loads. The structure makes copies of current, so it's called a current mirror. Current mirrors are crucial amplifier building blocks, and being able to recognize them will let you pick apart tricky schematics. We can also cover them in one lecture, which is important as we lead up to the midterm: we don't want to be introducing big long analyses right now.

The Simple Current Mirror

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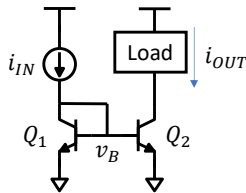
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In this video we're going to get started with current mirrors by analyzing the simplest one, which is conveniently called the simple current mirror. By the way, that name is a warning: there might be a few complicated current mirrors out there, so let's enjoy our time with this one.

Current Mirrors Set $i_{OUT} \approx i_{IN}$



$$i_{C1} = I_{S1} \left(\exp\left(\frac{v_B}{\phi_t}\right) - 1 \right) \leftrightarrow v_B = \phi_t \ln\left(1 + \frac{i_{C1}}{I_{S1}}\right)$$

$$i_{C2} = i_{C1} \quad \text{because} \quad v_{B2} = v_{B1} = v_B$$

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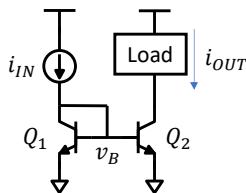
The simple current mirror is pictured on the left here. The title gives away its big trick, which is that the current i_{OUT} is forced to be the same as the i_{IN} current source.

CLICK The heart of that trick is that v_B is a one-to-one function of i_C . So the i_{IN} current source creates some amount of i_{C1} in the diode connected Q_1 , and we can invert the i_{C1} equation to find that v_B is set to the value that produces i_{C1} of current.

CLICK That means the i_{C1} current must match the i_{C2} current because both transistors share the same base voltage, v_B , which we already know is appropriate to create i_{C1} . Great! Now all we need to do is find the relationship between i_{C1} and i_{IN} .

Before we do that, I want to take a tiny aside to mention that current mirrors are an interesting structure because you could argue that they use a technique called predistortion. Q_1 converts i_{IN} to v_B through a non-linear function, and Q_2 uses the inverse of that non-linear function to create i_{OUT} . So we're using Q_1 to pre-distort the i_{IN} signal. That means we're deliberately leveraging non-linear operation of these devices, and we don't rely on a small signal model here. That's cool! It's also why I've been using total signal notation throughout.

BJT Current Mirrors Have Small Errors



$$i_{C1} = \beta i_{B1} \quad \text{b/c } Q_1 \text{ guaranteed in FAR by diode connection}$$

$$i_{B1} = i_{B2} \quad \text{b/c } Q_1 \text{ and } Q_2 \text{ have the same } v_B$$

$$i_{IN} = i_{C1} + i_{B1} + i_{B2}$$

$$i_{IN} = i_{B2}(1 + 1 + \beta)$$

$$i_{OUT} = \beta i_{B2} = i_{IN} \frac{\beta}{\beta + 2}$$

$$\epsilon = \frac{\beta}{\beta + 2} \approx 98\% \quad \text{for simple current mirrors}$$

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Alright, back to relating i_{C1} , which is equal to i_{C2} , to i_{IN} .

CLICK First, we observe that i_{C1} has to be βi_{B1} because Q_1 is in forward active. We know it's in forward active because it's diode connected, and diode connected devices are either in forward active or cutoff.

CLICK Second, we recall from the previous slide that i_{B1} has to be the same as i_{B2} because v_B is the same on both devices. Note that this equation is assuming Q_1 is identical to Q_2 , which isn't all that safe of an assumption in normal transistor manufacturing processes. Mismatch in Q_1 and Q_2 results in current mismatch, and we'll look at that in more detail later.

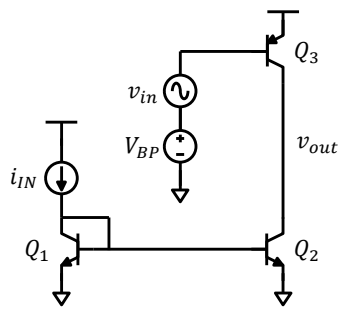
CLICK Then we write KCL at the v_B node, noting that two base currents and one collector current flow out of it, while i_{IN} flows in.

CLICK We can substitute values in for i_{C1} and i_{B1}

CLICK and finally note the relation between i_{B2} and i_{C2} and rearrange a bit to get this final relation between i_{IN} and i_{OUT} . There's a slight mismatch between i_{IN} and i_{OUT} that comes from the base currents stealing a bit of i_{IN} .

CLICK We capture that in an important current mirror parameter called the error factor, or epsilon. It's the ratio of i_{OUT}/i_{IN} , and for simple mirrors it's about 98%. A 2% error is actually quite high, and there are lots of trickier mirrors that reduce this error. We're only going to study one of them in detail because this error is somewhat unique to BJTs: other transistors, like MOSFETS, mostly don't have base current. As a result, this type of analysis -- which I call an error problem, by the way -- is almost never done in the real world. That means I'm not going to hold you responsible for doing any, which is kind of a shame because it's sort of satisfying analysis to chase KCL around a circuit.

Current Mirrors Let Us Bias Active Loads

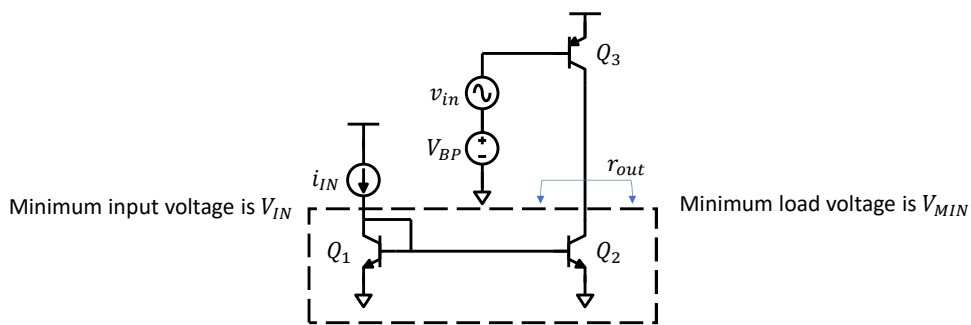


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Great, so now we know how a current mirror works and that it basically makes $i_{OUT} = i_{IN}$, within a small margin of error. Why do we care?

The answer is that current mirrors are very handy for biasing circuits, especially circuits with active loads. Here we've used the Q1/Q2 current mirror to set the collector current of Q3, which we could only do with tricky graphical analysis before. We still need to get V_{BP} right for this circuit to work, but we don't also have a sensitive bias voltage on the base of Q2. It turns out that current mirrors can help bias Q3 as well, we'll see more on that later. We've also introduced a new problem, which is making the i_{IN} current source. Though we generally only control voltages in lab, making a current source that only produces one current using transistors is reasonably straightforward. More on that later too.

Current Mirrors Described By Parameters



$$\text{For this mirror: } V_{IN} = V_{BEON1} \quad r_{out} = r_{o2}$$

$$V_{MIN} = V_{CESAT2} \quad \epsilon = \frac{\beta}{\beta + 2}$$

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We've already talked about error as a parameter of current mirrors, but seeing them in this application as active loads is a hint at a few other important current mirror parameters. It's helpful to define the boundaries of our current mirror when we talk about these parameters, so I've included a dotted line that surrounds our current mirror in the schematic above. The box has an input wire on the left, where i_{IN} enters the mirror, and we expect that current to be copied to the output wire on the right.

CLICK In order for that to happen, we need to make sure to maintain some minimum voltage on the input wire to keep the mirror devices in forward active. That voltage is called V_{IN} , and it's a current mirror parameter.

CLICK Similarly, we need to keep all the devices in the mirror in forward active, which means there will be some minimum voltage on the output wire too. That voltage is called V_{MIN} .

CLICK Finally, because mirrors are used as active loads so often, it's important to calculate their small signal output impedance, r_{out} . Note that this is a small signal parameter, while V_{IN} and V_{MIN} are large signal parameters.

Pause the video and try to find V_{IN} , V_{MIN} and r_{out} for this simple current mirror.

CLICK V_{IN} is V_{BEON1} because the diode connected device needs to stay in forward active, which requires v_B be high enough to turn on the Q1 base-emitter diode. V_{MIN} is V_{CESAT2} because we need to keep Q2 from saturating. It's guaranteed to be in forward active by v_B unless its collector voltage dips too low. An output source connected to the output of the mirror would just see r_{o2} to ground because the Q2 gm generator is shut off by the diode connected transistor connecting the base to ground. That means r_{out} is just r_{o2} .

... this sets i_C in Q3 to be the same as Q2, which biases the whole circuit.

... We still need to get V_{BP} just right so that it tells Q3 to have the same current as Q2, and we still need to figure out how to make i_{IN}

Summary

- Current mirrors set $i_{OUT} \approx i_{IN}$.
- BJT current mirrors have small error factors, which we label ϵ
- Current mirrors can help us bias actively loaded amplifiers.
- Current mirror design parameters are V_{IN} , V_{MIN} , ϵ and r_{out}

Current Mirror with Beta Helper

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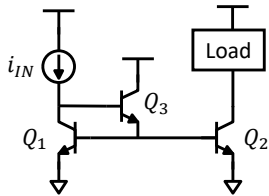
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In this video we're going to analyze another current mirror, which is called a current mirror with a beta helper. We're doing this mostly to introduce the idea of a beta helper, which is a trick that shows up all over BJT designs. We're going to do one more error analysis in this video because it helps explain what the beta helper is doing, but remember that I don't think being able to do error analysis is super important to the engineers of today.

Beta Helpers Help Source Base Current



$$i_{OUT} = i_{C2} = \beta i_{B2}$$

$$i_{E3} = i_{B1} + i_{B2} = 2i_{B2} = (\beta + 1)i_{B3}$$

$$i_{IN} = i_{C1} + i_{B3}$$

$$= \beta i_{B2} + \frac{2}{\beta + 1} i_{B2}$$

$$= i_{OUT} \left(1 + \frac{2}{\beta^2 + \beta} \right)$$

$$\epsilon = \frac{\beta^2 + \beta}{\beta^2 + \beta + 2} \approx 99.98\%$$

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Q3 in this circuit is called a beta helper, and it helps to source the base current for Q1 and Q2 so that i_{IN} doesn't see that base current pulled away. You might notice that Q3 looks a bit like an emitter follower, and that's a good observation. It's acting like a voltage buffer, creating a copy of its base voltage at its emitter, which makes i_{IN} see a much bigger input impedance. That means Q1 is still kind-of diode connected like the current mirror, just in a fancy way with a voltage buffer in the middle.

If you want to try an error calculation, you can pause the video and give this one a shot. That's optional though because I'm not holding your feet to the fire for error calculations, but this one is a reasonably satisfying and quick problem.

CLICK We start our analysis by noting that i_{OUT} is equal to i_{C2} , which is βi_{B2} because we usually assume everything is operating in forward active in a mirror.

CLICK The emitter of Q3 sees provides both base currents to Q1 and Q2, and those base currents are the same because the base voltage on Q1 and Q2 is the same. We can also relate those base currents to the base current of Q3, by noting that i_{E3} is equal to $\beta + 1$ times i_{B3} .

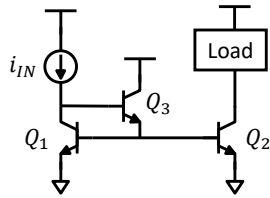
CLICK KCL at the collector of Q1 lets us see that i_{IN} is equal to $i_{C1} + i_{B3}$.

CLICK and we can use substitutions from the second line to express i_{C1} as β times i_{B2} (because i_{B2} is the same as i_{B1}) and i_{B3} in terms of i_{B2} .

CLICK We can rearrange and use our relation between i_{C2} and i_{B2} to write i_{IN} in terms of i_{OUT} .

CLICK Finally, a little more rearranging gives us our error factor, which is about 99.98%. 0.02% is an acceptably low error, and we have our Q3 voltage buffer to thank for it.. Thanks, beta helper!

Beta Helpers Increase V_{IN}



$$V_{IN} = 2V_{BEON}$$

$$V_{MIN} = V_{CESAT}$$

$$r_{out} = r_o$$

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Calculating the other current mirror parameters for this current mirror is pretty straightforward. Pause the video and try to find V_{IN} , V_{MIN} and r_{out} .

CLICK V_{IN} has increased to $2V_{BEON}$ because we need to keep both Q1 and Q3 in forward active. V_{MIN} is still V_{CESAT} because we're only worried about Q2 getting into saturation. r_{out} is still r_o because the output of the emitter follower just sees the collector of Q2 on its path to ground. We've paid a bit of V_{IN} to have our good error performance, and many current mirror designs try to break that tradeoff.

Summary

- Beta helps source base current.
- The beta helper in this current mirror increased V_{IN} .
- Current mirrors generally come with similar design tradeoffs.

Cascode Current Mirror

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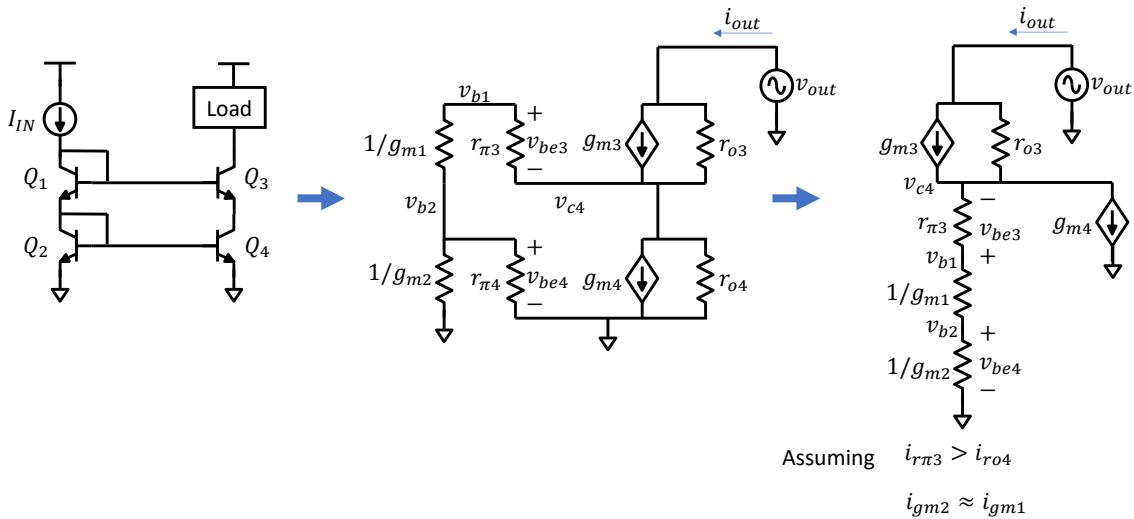
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In this video we're going to analyze cascode current mirrors because they get used quite a bit. These are interesting because of their high rout, which will give us a chance to try small signal analysis on mirrors.

Cascode Current Mirrors Have High r_{out} .

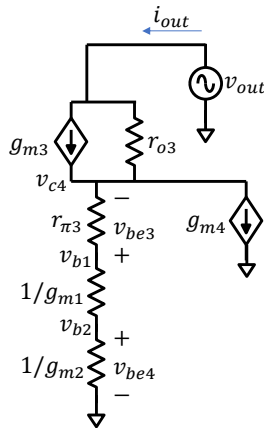


A cascode mirror appears on the left of this slide. I just promised that cascode mirrors have high r_{out} and we're going to prove it on the next two slides. Doing so will require small signal models. Pause the video and try making a small signal model for the cascode current mirror pictured here. Note that I've labeled I_{IN} as a large signal current source, which is typical when you're trying to create stable bias currents using mirrors. Note also that the diode connected devices have turned into $1/g_m$ resistors.

CLICK Here's a complicated looking small signal model, where I've just substituted our hybrid pi model in for the large signal circuit. Note that I_{IN} becomes an open circuit here. Note also that this is a mess!

CLICK Here's my attempt to simplify it. I made two assumptions to do so, which is that not much current flows into r_{o4} instead of $r_{\pi3}$ – so I left r_{o4} as an open circuit – and that not much current flows into $r_{\pi4}$ instead of $1/g_{m2}$, so I left $r_{\pi4}$ out of the drawing. This model is troubling because it's not one of our small signal patterns, which might mean that we have to reinvent the wheel by grinding away with KVL and KCL in the circuit.

Cascode Current Mirrors Have High r_{out}



$$i_{out} = i_{r\pi3} + i_{gm4}$$

$$i_{gm4} = g_{m4} \left(\frac{i_{r\pi3}}{g_{m2}} \right) \approx i_{r\pi3} \quad \text{Makes sense b/c current mirror}$$

$$i_{out} \approx 2i_{r\pi3}$$

$$-v_{be3} \approx \frac{i_{out}}{2} r_{\pi3} \approx v_{c4} \quad \text{Redoing left-right pattern w/ } i_{out}/2$$

$$i_{out} = i_{gm3} + i_{r_{o3}}$$

$$= \frac{g_{m3} r_{\pi3}}{2} i_{out} + \frac{v_{out} - i_{out} r_{\pi3}/2}{r_{o3}}$$

$$r_{out} \approx \frac{\beta_3 r_{o3}}{2}$$

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I'm going to find r_{out} on this slide, but I encourage you to pause the video and take a run at it first. This is a tricky small signal problem, and it's easier if you make a bunch of assumptions. I'm going to do that in my solution to focus in on the insights you can take away about the circuit's operation. However, if you want to solve it in all its glory, then you will get good practice with small signal models. Pause the video now if you want to try.

CLICK Our usual left-right pattern analysis assumes all of our test current flows in the tail resistance below the current source, but that isn't true here. Instead we have this additional g_{m4} source dangling off the side of our analysis and eating up part of i_{out} . Finding that i_{gm4} and kicking it out of our analysis will make our life easier.

CLICK Fortunately, its control voltage is pretty easy to find. We know that v_{be4} is going to be whatever current is flowing in the $r_{\pi3}$ branch times $1/g_{m2}$, and we further know that i_{gm4} is just g_{m4} times that quantity. Q2 and Q4 were designed as part of a current mirror, so it's likely that g_{m4} is pretty close to g_{m2} (though relaxing that constraint lets you play some neat biasing tricks), which means that i_{gm4} is about equal to $i_{r\pi3}$. That means the current that enters the v_{c4} node just splits in half between the two branches. That seems like a suspiciously convenient result, and there's a good reason for it. Q2 and Q4 are a current mirror, and current mirrors guarantee that the total signal i_{IN} matches the total signal i_{OUT} , which means that they make the same guarantee for small signals that are part

of a total signal. The current is splitting in half because the Q2/Q4 current mirror is forcing current in both Q2 and Q4 collectors to be equal.

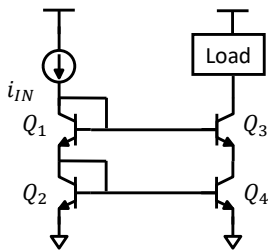
CLICK OK, so after this, we can just redo the usual left-right pattern analysis using a reduced value of i_{out} passing through $r_{\pi 3}$. I've included this line to indicate a simplifying assumption I'm making for the rest of the analysis, which is that $r_{\pi 3}$ is bigger than $1/g_{m1} + 1/g_{m2}$, so we can just ignore those resistors when we calculate v_{c4} . That lets us say that v_{c4} is about the same as v_{be3} .

CLICK So we write KCL at the i_{out} node on top of the structure

CLICK Then substitute in the g_{m3} current value based on v_{be3} and the r_{o3} current value based on the difference between v_{out} and v_{c4} , which is close to v_{be3} . At this point, the equation looks like our usual right-left pattern equation with just a few funny factors. However, you can see that clearing the r_{o3} from the denominator of the rightmost term will give us a factor of $\beta_3 * r_{o3}/2$ times i_{out} in the leftmost term.

CLICK And that term winds up dominating the equation, so our final expression for output resistance of a cascode mirror will be about $\beta_3 * r_{o3}/2$. That's half the resistance of a cascode amplifier, and it's cut in half by the action of the Q2/Q4 mirror.

Other Cascode Mirror Parameters Middling



$$\epsilon = \frac{\beta^2}{\beta^2 + 4\beta + 2} \approx 96\%$$

$$V_{IN} = 2V_{BEON}$$

$$V_{MIN} = V_{BEON} + V_{CESAT}$$

Epsilon is also involved for a cascode amplifier so I've just included it on this slide. It's worth noting that the error is pretty middling. The other cascode amplifier parameters are easier to find. Pause the video and find V_{IN} and V_{MIN} .

CLICK V_{IN} is $2V_{BEON}$ to keep Q1 and Q2 in forward active. In general, diode connected devices require a V_{BEON} drop across them, just like a diode. V_{MIN} is a bit trickier. It's $V_{BEON} + V_{CESAT}$ because the emitter of Q3 is pinned to V_{BEON} by Q1 and Q2. You pick up V_{BEON} going up Q2, and then an addition V_{BEON} going up Q1, then you drop a V_{BEON} on the base-emitter junction of Q3. Finally, you need to keep the output at least V_{CESAT} above the emitter to keep Q3 from saturation. This practice of navigating around a large signal circuit by climbing up and down V_{BEON} values is really common, you should look for opportunities to do it.

Summary

- Cascode current mirrors have a high $r_{out} = \beta r_o/2$.
- Other cascode mirror parameters are only OK
 - $V_{IN} = 2V_{BEON}$
 - $V_{MIN} = V_{BEON} + V_{CESAT}$
 - Error factor ~96%
- Beware of tricky small signal models that defy our patterns.