

# E11 Lecture 2: Introduction to C

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# Outline

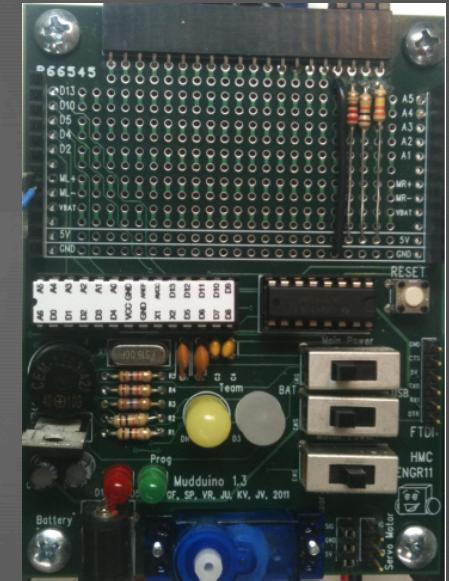
- What is C?
- Programming Target: Arduino
- Programming Basics
  - Simple C Program
  - Running a Program
- Programming Tools
  - Comments
  - Data Types
  - Variables
  - Console Inputs and Outputs
- More stuff you can do...

# What is C?

- **Created by Dennis Ritchie at Bell Laboratories in 1972**
- **Programming language for making a computer/microcontroller do something.**
- **One of the most popular programming languages:**
  - Available for many platforms (supercomputers to embedded microcontrollers)
  - Relatively easy to use, moderate level of abstraction, but programmer also has an idea of how code will be executed
  - Can interact with hardware directly

# Programming Target: Arduino

- Arduino
  - type of microcontroller
  - we'll talk about this a lot more next time
- Overall syntax is same as C
- Some differences (we'll highlight them)
- FYI, Arduino's version of C is called "Arduino"



# Simple C Program

```
void setup ()  
{  
}  
}
```

}

This runs first  
(sets things up)

```
void loop ()  
{  
}  
}
```

}

Then this runs repeatedly  
(it loops)

All programs **MUST** contain these two functions

# Simple C Program: Example

```
void setup()
{
    Serial.begin(9600);
    Serial.println("Hello world!");
}

void loop()
{}
```

# Simple C Program: Example

```
void setup()
{
    Serial.begin(9600) ;
```

Setup serial port to  
run at 9600 baud → (bits/second)

```
    Serial.println("Hello world!") ;
```

Print “hello world!” to  
the serial port → (followed by a  
carriage return)

```
}
```

```
void loop() ←
{
```

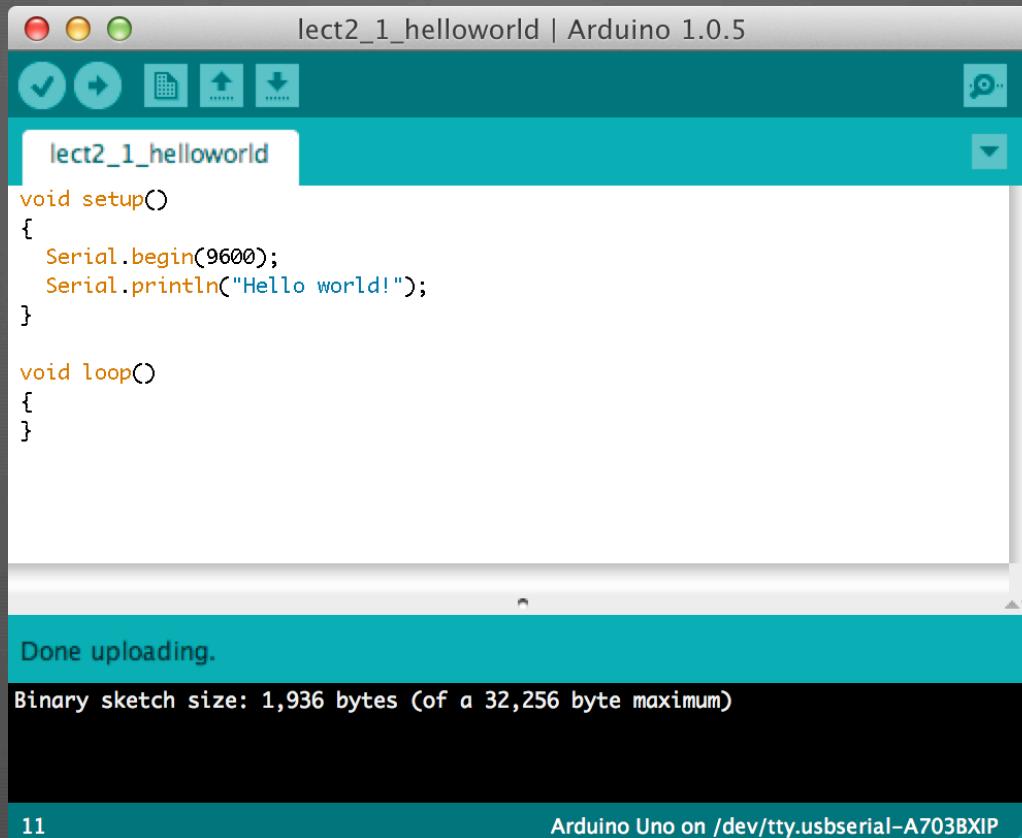
In this program, the  
loop() function does  
nothing (but still must  
be included!)

# Running a Program on the Arduino

- Run the Arduino software: *arduino.exe*
  - [arduino.cc/en/Main/Software](http://arduino.cc/en/Main/Software)
- Type the program into the *sketch*
- Save the file using a meaningful name – e.g.“helloworld”
  - From the file menu: File -> Save As
  - The file will save with the .ino extension (helloworld.ino)
- Connect the Arduino board using an FTDI USB cable
  - Black wire goes to GND
- Change the settings to the correct device and port
  - From the file menu: Tools -> Board -> Arduino Uno
  - Check the USB port settings with Tools -> Serial Port
    - Random COM port on Windows
    - /dev/tty.usbserial-randomcharacters on mac
- Verify the code
- Upload the code
- Open the Serial Monitor (after the code uploads)

# Running a Program on the Arduino (cont.)

- Run the Arduino software: *arduino.exe*
- Type the program into the *sketch*



The screenshot shows the Arduino IDE interface. The title bar reads "lect2\_1\_helloworld | Arduino 1.0.5". The main window displays the following Arduino C++ code:

```
lect2_1_helloworld

void setup()
{
    Serial.begin(9600);
    Serial.println("Hello world!");
}

void loop()
{}
```

At the bottom of the IDE, a status bar indicates "Done uploading." and "Binary sketch size: 1,936 bytes (of a 32,256 byte maximum)".

# Demo

# Coding: Your Turn!

Write a program that repeatedly prints the phrase: “I love E11 already!”

# Coding: Your Turn!

Write a program that repeatedly prints the phrase: “I love E11 already!”

```
void setup()
{
    Serial.begin(9600);
}

void loop()
{
    Serial.println("I love E11 already!");
}
```

# Outline

- What is C?
- Programming Target: Arduino
- Programming Basics
  - Simple C Program
  - Running a Program
- Programming Tools
  - Comments
  - Data Types
  - Variables
  - Console Inputs and Outputs
- More stuff you can do...

# Comments

- Are ignored by the computer running the program
- But are **critical** for clarity and organization
- Single-line comment

```
// single-line comment
```

- Multiple-line comments

```
/* multiple-line  
comment */
```

# Data Types

- A data type tells us:
  - The **type** of values represented
  - The **range** of values

# Data Types

Type	Size (bits)	Minimum	Maximum
char	8	$-2^7$ (-128)	$2^7 - 1$ (127)
unsigned char	8	0	$2^8 - 1$ (255)
int	16	$-2^{15}$ (-32,767)	$2^{15} - 1$ (32,768)
unsigned int	16	0	$2^{16} - 1$ (65,535)
long	32	$-2^{31}$ (-2,147,483,648)	$2^{31} - 1$ (2,147,483,647)
unsigned long	32	0	$2^{32} - 1$ (4,294,967,295)
float	32	$\pm 2^{-126}$	$\pm 2^{128} * (2-2^{-15})$
boolean	8	false	true

**Note:** byte = unsigned char  
double = float  
word = unsigned int

# Binary Numbers: Range

- What happens when a result won't fit in that range?
  - Overflow!
  - For example, with only 2 bits:  
 $11 + 01 = 100 = 00!$

# Overflow Example

```
void setup()
{
    char x = 33;
    char y = 257;
    Serial.begin(9600);

    Serial.print("The value of x is ");
    Serial.println(x, DEC);

    Serial.print("The value of y is ");
    Serial.println(y, DEC);
}

void loop()
{}
```

# Variables

- Each variable has a:
  - Name
  - Type
  - Value

## Example:

```
int cnt = 5; // name is cnt, type is int, value is 5
```

# Variables

```
int count = 0; // global variable

void setup() {
    char x;           // local variables
    float y = 7.8;
    boolean found = false;

    x = 12;          /* x is initialized
                        after it is
                        declared. */

    ...
}
```

# Variables

- All variables must be *initialized* (set to a known value) before they are used
- Global variables:
  - are declared outside of all functions
  - are accessible anywhere in the program
- Local variables
  - are declared within a function
  - are only accessible within that function

# Variables

```
int cnt = 0;

void setup() {
    char x;
    float y = 7.8;
    boolean found = false;

    x = 12;
    ...
}

void loop()
{
    cnt = 42;
    x = 3;
}
```

# Coding: Your Turn!

Write a program that converts the variable `x` from centimeters to inches and prints the value of `x` in both units.

```
// convert x from cm to in  
int x = 12;
```

# Coding: Your Turn!

Write a program that converts the variable x from centimeters to inches and prints the value of x in both units.

```
// convert x from cm to in
int x = 12;
float y = 12/2.54;

Serial.print("x = "); Serial.print(x);
Serial.print(" cm = "); Serial.print(y);
Serial.println(" inches.");
```

# Console Input and Output

- Output
  - `Serial.print(string or variable name);`
  - `Serial.println(string or variable name);`
- Input
  - `int Serial.read();`

# Console Input and Output Example

```
void setup()
{
    Serial.begin(9600); // opens serial port at 9600 baud
    Serial.println("Enter a value: ");
}

void loop() {
    int incomingByte = 0; // incoming serial data

    // read user input
    if (Serial.available() > 0) {
        incomingByte = Serial.read();

        // print result:
        Serial.print("I received: ");
        Serial.println(incomingByte, HEX);
    }
}
```

# ASCII

In my eyes,  
that should  
be spelled  
**ASCIII**



Binary	Octal	Decimal	Hexadecimal	Glyph
010 0000	040	32	20	space
010 0001	041	33	21	!
010 0010	042	34	22	"
010 0011	043	35	23	#
010 0100	044	36	24	\$
010 0101	045	37	25	%
010 0110	046	38	26	&
010 0111	047	39	27	'
010 1000	050	40	28	(
010 1001	051	41	29	)
010 1010	052	42	2A	*
010 1011	053	43	2B	+
010 1100	054	44	2C	,
010 1101	055	45	2D	-
010 1110	056	46	2E	.
010 1111	057	47	2F	/
011 0000	060	48	30	0
011 0001	061	49	31	1
011 0010	062	50	32	2
011 0011	063	51	33	3
011 0100	064	52	34	4
011 0101	065	53	35	5
011 0110	066	54	36	6
011 0111	067	55	37	7
011 1000	070	56	38	8
011 1001	071	57	39	9
011 1010	072	58	3A	:
011 1011	073	59	3B	;
011 1100	074	60	3C	<
011 1101	075	61	3D	=
011 1110	076	62	3E	>
011 1111	077	63	3F	?

Binary	Octal	Decimal	Hexadecimal	Glyph
100 0000	100	64	40	@
100 0001	101	65	41	A
100 0010	102	66	42	B
100 0011	103	67	43	C
100 0100	104	68	44	D
100 0101	105	69	45	E
100 0110	106	70	46	F
100 0111	107	71	47	G
100 1000	110	72	48	H
100 1001	111	73	49	I
100 1010	112	74	4A	J
100 1011	113	75	4B	K
100 1100	114	76	4C	L
100 1101	115	77	4D	M
100 1110	116	78	4E	N
100 1111	117	79	4F	O
101 0000	120	80	50	P
101 0001	121	81	51	Q
101 0010	122	82	52	R
101 0011	123	83	53	S
101 0100	124	84	54	T
101 0101	125	85	55	U
101 0110	126	86	56	V
101 0111	127	87	57	W
101 1000	130	88	58	X
101 1001	131	89	59	Y
101 1010	132	90	5A	Z
101 1011	133	91	5B	[
101 1100	134	92	5C	\
101 1101	135	93	5D	]
101 1110	136	94	5E	^
101 1111	137	95	5F	_

# Console Input and Output Example

```
int incomingByte = 0; // incoming serial data

void setup()
{
    Serial.begin(9600); // opens serial port at 9600 baud
    Serial.println("Enter a value: ");
}

void loop() {
    // read user input
    if (Serial.available() > 0) {
        incomingByte = Serial.read();

        // print result:
        Serial.print("I received: ");
        Serial.println(incomingByte, DEC);
    }
}
```

# Print Formats

- Print formats

`Serial.print(val, format)`

`Serial.println(val, format)`

- *val* is value to print (any data type)
- *format* is:
  - DEC (decimal)
  - HEX (hexadecimal)
  - OCT (octal)
  - BIN (binary)
  - BYTE (ASCII-interpreted byte)
  - or number of decimal places (for floating point)

# Physical Inputs and Outputs

- **Setup:**
  - `pinMode(pin, mode)`
  - *mode* is either: INPUT or OUTPUT
- **Output – setting a pin value:**
  - `digitalWrite(pin, value)`
  - *value* is either: HIGH or LOW
- **Input:**
  - `digitalRead(pin)`

# Physical Output: LED

```
void setup()
{
    Serial.begin(9600);

    // set LED pin as output
    pinMode(13, OUTPUT); // LED pin
}

void loop()
{
    Serial.println("Testing LED");

    digitalWrite(13, HIGH); // turn the LED on
    delay(200);           // delay 200 ms

    digitalWrite(13, LOW); // turn the LED off
    delay(200);           // delay 200 ms
}
```

# Physical Output: Speaker

```
void setup()
{
    Serial.begin(9600);

    // set speaker pin and LED as outputs
    pinMode(4, OUTPUT); // speaker pin
    pinMode(13, OUTPUT); // LED pin
}

void loop()
{
    Serial.println("Testing speaker");

    tone(4, 440); // write tone of 440 Hz to speaker
    digitalWrite(13, HIGH); // turn the LED on
    delay(200); // delay 200 ms
    noTone(4); // turn the speaker (pin 4) off
    digitalWrite(13, LOW); // turn the LED off
    delay(200); // delay 200 ms
}
```

<http://arduino.cc/en/Reference/HomePage>

# Useful Resource!!!

The screenshot shows a Mac OS X desktop with a window titled "Arduino - Reference". The address bar indicates the page is at <http://arduino.cc/en/Reference/HomePage>. The browser's toolbar includes icons for back, forward, search, and refresh, along with links to Gmail, CS5, CS6, CS154, ACM, USACO, home, csReq, VEMS, F+M, RobWiki, trac, and NYT.

The main content area displays the Arduino Language Reference. At the top left is the "Arduino" logo. A search bar is located at the top right. Below the logo, there are links for "Buy | Download | Getting Started | Learning | Reference | Hardware | FAQ" and "Blog > | Forum > | Playground >".

The "Language Reference" section is currently active. It contains a navigation menu with links to "Reference", "Language", "Libraries", "Comparison", and "Changes".

The page is organized into several sections:

- Structure**:
  - setup()
  - loop()
- Control Structures**:
  - if
  - if...else
  - for
  - switch case
  - while
  - do... while
  - break
  - continue
  - return
  - goto
- Further Syntax**:
  - ;(semicolon)
  - { } (curly braces)
  - // (single line comment)
  - /\* \*/ (multi-line comment)
  - #define
  - #include
- Arithmetic Operators**: (This section is partially visible at the bottom)
- Variables**:
  - Constants
    - HIGH | LOW
    - INPUT | OUTPUT
    - true | false
    - Integer constants
    - Floating point constants
  - Data Types
    - void
    - boolean
    - char
    - unsigned char
    - byte
    - int
    - unsigned int
    - word
    - long
    - unsigned long
    - float
    - double
    - string - char array
    - String - object
    - array
- Functions**:
  - Digital I/O
    - pinMode()
    - digitalWrite()
    - digitalRead()
  - Analog I/O
    - analogReference()
    - analogRead()
    - analogWrite() - PWM
  - Advanced I/O
    - tone()
    - noTone()
    - shiftOut()
    - pulseIn()
  - Time
    - millis()
    - micros()
    - delay()
    - delayMicroseconds()
  - Math
    - min()