# Asynchronous Serial Interfaces and the Internet of Things

Lecture 12

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#### Outline

- Serial Interfaces pt. 2 the Universal Synchronous/Asynchronous Receiver Transmitter
- General Internet Architecture
  - Protocol layers
  - Browsing the Web
  - HTTP Commands and Format
  - HTML Hypertext Markup Language
- ESP8266
  - Overview
  - Lab 7 Webserver Code
  - Basic workflow for whole system

## **Learning Objectives**

By the end of this lecture you should be able to...

- Articulate the differences and tradeoffs between a synchronous serial link (e.g., SPI) and an asynchronous serial link.
- Use the USART peripheral on the MCU to print to the terminal window
- Write a basic HTML webpage
- Explain the basic operating principles of an HTTP webserver

# Universal Synchronous/Asynchronous Receiver Transmitter (USART)

## What if we don't want a shared clock?

We must...

- Agree on shared data rate
- Sample the incoming data stream at higher frequency to synchronize the input data stream with the reading circuitry
- Add additional bits at the beginning and end of the transmission to signal the bounds of the transmission

Q: What are some downsides of an asynchronous serial interface as compared to a synchronous one?

• Reduced

(typically 8x-16x overhead from sampling)

• Wasted in each transmission

#### **USART Data Frame**

4 components

- 1. Start bit: always logical 0
- 2. Data bits: 5-9 bits of data
- 3. Parity bit: Option bit with parity of data (i.e., even or odd. Simple error checking)
- 4. Stop bit(s): 1-2 bits. Always logical 1.



#### STM32L432KC USART



Figure 382. USART block diagram

#### **Data Registers**



RM0394 p. 1198

#### Pins

- TX transmitted data out from USART
- RX received data in to USART
- CK (optional) clock output for synchronous mode
- RTS Request To Send indicates the USART is ready to receive data (when low)
- CTS Clear To Send block data transmission at the end of the current transfer when high

#### Data framing

#### Data framing



Figure 384. Configurable stop bits

RM0394 p. 1202

9

## **Error Flags**

- Overrun new byte in the before the old one was read out
- Frame didn't get the we expected
- Parity calculated doesn't match

#### Receiver





#### USART registers: Interrupt and Status Register (ISR)

UART Status Register

- TXE transmit data register empty (0 if data is not transferred to the shift register, 1 if it is)
- TC transmission complete flag
- RXNE read data register not empty (0 if data has not been received, 1 if it is ready to be read)
- FE framing error
- PE parity error

#### 38.8.8 Interrupt and status register (USART\_ISR)

Address offset: 0x1C

Reset value: 0x0200 00C0

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Res.	Res.	Res.	Res.	Res.	Res.	TCBGT	Res.	Res.	REACK	TEACK	WUF	RWU	SBKF	CMF	BUSY
						r			r	r	r	r	r	r	r
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ABRF	ABRE	Res.	EOBF	RTOF	CTS	CTSIF	LBDF	TXE	TC	RXNE	IDLE	ORE	NF	FE	PE
r	r		r	r	r	r	r	r	r	r	r	r	r	r	r

## **USART registers: Data Register**

- Used for both reads and writes
- Max 9-bit data value DR [8:0]

#### **USART registers: Baud Rate Register**

#### 38.8.4 Baud rate register (USART\_BRR)

This register can only be written when the USART is disabled (UE=0). It may be automatically updated by hardware in auto baud rate detection mode.

Address offset: 0x0C

Reset value: 0x0000 0000

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Res.	Res.	Res.	Res.	Res.	Res.	Res.	Res.								
15	. 14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							BRR	[15:0]							
rw	rw	rw	rw	rw	rw	rw	rw								

Bits 31:16 Reserved, must be kept at reset value.

Bits 15:4 BRR[15:4]

BRR[15:4] = USARTDIV[15:4]

Bits 3:0 BRR[3:0]

When OVER8 = 0, BRR[3:0] = USARTDIV[3:0]. When OVER8 = 1: BRR[2:0] = USARTDIV[3:0] shifted 1 bit to the right. BRR[3] must be kept cleared.

### **USART registers: Control register 1**

- M: word length 8 or 9 data bits
- PCE: parity control enable
- TE: transmitter enable
- RE: receiver enable

#### **USART registers: Control register 2**

- **STOP**: 2-bit field, number of stop bits (0.5, 1, or 2)
- Various clock control (if using in synchronous mode)

#### 38.8.2 Control register 2 (USART\_CR2)

Address offset: 0x04

Reset value: 0x0000 0000

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
	ADD	[7:4]			ADD	[3:0]		RTOEN	ABRM	OD[1:0]	ABREN	MSBFI RST	DATAINV	TXINV	RXINV
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SWAP	LINEN	STO	P[1:0]	CLKEN	CPOL	CPHA	LBCL	Res.	LBDIE	LBDL	ADDM7	Res.	Res.	Res.	Res.
rw	rw	rw	rw	rw	rw	rw	rw		rw	rw	rw				

#### **Character Reception**

1. Program the M bit in USART\_CR1 to define word length

- 2. Program the sampling rate (x8 or x16) in USART\_CR1
- 3. Program the number of stop bits in USART\_CR2
- 4. (optional): Enable DMA
- 5. Select the desired baud rate in USART\_BRR
- 6. Enable the USART with UE=1 in USART\_CR1
- 7. Set the RE bit in USART\_CR1

Wait for RXNE bit to go from 0 (no data received) to 1 (data received). Then, read out the data from the data register

#### **USART Instances**







# **USART** Activity

## Activity

Configure the USART as an UART to transmit serial data

- Read user manual and develop a bullet list outline of how to configure the peripheral
- Write USART library
- Finish STM32L432KC\_USART.h and STM32L432KC\_USART.c.
- Configure in common 8N1 mode
  - 8 data bits
  - No parity bit
  - 1 stop bit
  - Operate at 9600 baud (9.6 Kbps)
  - UART is configured to use the HSI which is 16 MHz.
- Use simple main function to transmit a string of your choice over the UART.

#### **Bits to configure**

#### 38.8.1 Control register 1 (USART\_CR1)

Address offset: 0x00

Reset value: 0x0000 0000

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Res.	Res.	Res.	M1	EOBIE	RTOIE			DEAT[4:0	]			I	DEDT[4:0	]	
			rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
OVER8	CMIE	MME	M0	WAKE	PCE	PS	PEIE	TXEIE	TCIE	RXNEIE	IDLEIE	TE	RE	UESM	UE
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

#### • UE: USART Enable

- M: Word Length
- OVER8: Oversampling mode
- TE: Transmitter Enable
- RE: Receiver Enable (In CR2)
- STOP: Number of stop bits

#### Setup

- Download source code from GitHub
- Create new SEGGER project
- Configure serial monitor to read at 9600 baud

				14610 1017 110	inate ranetter	/			
		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
P	ort	SYS_AF	TIM1/TIM2/ LPTIM1	TIM1/TIM2	USART2	12C1/12C2/12C3	SPI1/SPI2	SPI3	USART1/ USART2/ USART3
	PA0	-	TIM2_CH1	-	-	-	-	-	USART2_CTS
	PA1	-	TIM2_CH2	-	-	I2C1_SMBA	SPI1_SCK	-	USART2_RTS_ DE
	PA2	-	TIM2_CH3	-	-	-	-	-	USART2_TX
	PA3	-	TIM2_CH4	-	-	-	-	-	USART2_RX
	PA4	-	-	-	-	-	SPI1_NSS	SPI3_NSS	USART2_CK
	PA5	-	TIM2_CH1	TIM2_ETR	-	-	SPI1_SCK	-	-
	PA6	-	TIM1_BKIN	-	-	-	SPI1_MISO	COMP1_OUT	USART3_CTS
	PA7	-	TIM1_CH1N	-	-	I2C3_SCL	SPI1_MOSI	-	-
Port A	PA8	мсо	TIM1_CH1	-	-	-	-	-	USART1_CK
	PA9	-	TIM1_CH2	-	-	I2C1_SCL	-	-	USART1_TX
	PA10	-	TIM1_CH3	-	-	I2C1_SDA	-	-	USART1_RX
	PA11	-	TIM1_CH4	TIM1_BKIN2	-	-	SPI1_MISO	COMP1_OUT	USART1_CTS
	PA12	-	TIM1_ETR	-	-	-	SPI1_MOSI	-	USART1_RTS_ DE
	PA13	JTMS-SWDIO	IR_OUT	-	-	-	-	-	-
	PA14	JTCK-SWCLK	LPTIM1_OUT	-	-	I2C1_SMBA	-	-	-
	PA15	JTDI	TIM2_CH1	TIM2_ETR	USART2_RX	-	SPI1_NSS	SPI3_NSS	USART3_RTS_ DE

Table 15. Alternate function AF0 to AF7<sup>(1)</sup>

#### USART2 Wiring on Nucleo-32

#### 6.9 USART virtual communication

Thanks to SB2 and SB3, the USART interface of STM32 available on PA2 (TX) and PA15 (RX), can be connected to ST-LINK/V2-1. When USART is not used it is possible to use PA2 as Arduino Nano A7. Refer to *Table 7*.

Bridge	State <sup>(1)</sup>	Description
SB2	OFF	PA2 is connected to CN4 pin 5 as Arduino Nano analog input A7 and disconnected from ST-LINK USART.
	ON	PA2 is connected to CN4 pin 5 as Arduino Nano analog input A7 ar disconnected from ST-LINK USART.         PA2 is connected to ST-LINK as virtual Com TX (default).         F       PA15 is not connected.         N       PA15 is connected to ST-LINK as virtual Com RX (default).
<b>SD</b> 3	OFF	PA15 is not connected.
600	ON	PA15 is connected to ST-LINK as virtual Com RX (default).

Table 7. Virtual communication configuration

1. The default configuration is reported in bold style.

UM1956 p. 20

#### **USART2** Wiring



Figure 8. NUCLEO-L011K4, NUCLEO-L031K6, NUCLEO-L412KB and NUCLEO-L432KC pin assignment



UM1956 p. 33

## **Receiving Serial Input over USB**

#### Use built-in serial monitor in SES

Terminal Emulator
🗇 🔏 📑
Happy Hacking!

🔯 🧶 🛛 🗙

SEGGER Embedded Studio for ARM V6.34 - Terminal Emulator Pro...

#### Set terminal emulator properties

Option	Value
Terminal Emulator	
<ul> <li>Backscroll Buffer Lines</li> </ul>	500
<ul> <li>Baud Rate</li> </ul>	9600
Data Bits	8
<ul> <li>Flow Control</li> </ul>	None
<ul> <li>Line Feed On Carriage Return</li> </ul>	No
<ul> <li>Local Echo</li> </ul>	No
<ul> <li>Maximum Input Block Size</li> </ul>	4,096
<ul> <li>Parity</li> </ul>	None
Port	/dev/cu.usbmodem0007771802101
<ul> <li>Port Used By Target Interface</li> </ul>	No
Set DTR	No
<ul> <li>Stop Bits</li> </ul>	1

(No Property)



```
1
   . . .
 2
     // Set M = 00
     // M=00 corresponds to 1 start bit, 8 data bits, n stop bits
 3
     USART->CR1 &= \sim(USART CR1 M0 | USART CR1 M1);
 4
 5
     // Set to 16 times sampling freq
     USART->CR1 \&= ~USART CR1 OVER8;
 6
 7
     // 0b00 corresponds to 1 stop bit
 8
     USART->CR2 &= ~USART_CR2_STOP;
 9
10
11
     // Set baud rate to 115200 (see RM 38.5.4 for details)
12
     // Tx/Rx baud = f_CK/USARTDIV (since oversampling by 16)
     // f_CK = 16 MHz (HSI)
13
14
     USART->BRR = (uint16_t) (HSI_FREQ / baud_rate);
15
     // Enable USART
16
17
     USART->CR1 |= USART_CR1_UE;
18
     // Enable transmission and reception
19
     USART->CR1 |= USART_CR1_TE | USART_CR1_RE;
20
21
     return USART;
22 }
```

void sendChar(USART\_TypeDef \* USART, char data){
while(!(USART->ISR & USART\_ISR\_TXE));
USART->TDR = data;
while(!(USART->ISR & USART\_ISR\_TC));
}

```
1 // Lecture 12 Demo
 2 // Josh Brake
 3 // jbrake@hmc.edu
 4 // 10/5/22
 5
 6 #include "STM32L432KC.h"
 7 #include <stm32l432xx.h>
 8 #define USART_ID USART2_ID
 9 #define TIM TIM15
10
11 int main(void) {
12 // Configure flash and clock
13 configureFlash();
14 configureClock();
15
16 ...
```

```
1 ...
 2 // Initialize USART
 3 USART_TypeDef * USART = initUSART(USART_ID, 9600);
 4
 5 // Initialize timer
 6 RCC->APB2ENR |= RCC_APB2ENR_TIM15EN;
   initTIM(TIM);
 7
 8
9 char msg[28] = "Happy Hacking!\n\r";
10
11 while(1){
12
   int i = 0;
13
    do {
    sendChar(USART, msg[i]);
14
15
    i += 1;
    } while (msg[i]);
16
17
     delay_millis(TIM, 2000);
18
    }
19 }
```

# The Hypertext Transfer Protocol (HTTP)

#### **Protocol Layers**

1P - Internet Protocol Address



- Worldwide web is a service on the Internet
- Uses Hypertext Transfer Protocol (HTTP)
  - What layer is this protocol at?
- URL: Uniform Resource Locator
  - URL format: <protocol>://<hostname>:
     <port>/<path\_and\_filename>

## **Browsing the Web**

What happens when you type in a URL?

- Finds IP for domain if necessary (Using Dynamic Nameserver (DNS))
- Connects to server, send HTTP request
- Server receives request, searches for desired page.
  - If it exists, sends it.
  - If not, sends 404 "Page Not Found" error code.
- Web browser gets page, closes connection
- Parses webpage sending HTTP requests as necessary to get all the elements

#### **HTTP: Commands and Format**

GET

- Most common
- Used to request a resource
- Format
  - GET / HTTP/1.1 Host: Accept

Request Line	
Request Headers	Message Header
Blank Line	
Request Message Body (optional)	Message Body

## HTML: HyperText Markup Language

Simple text format to specify webpage formatting

- Elements
  - DOCTYPE statement
  - HTML tag
  - Head
  - Body
- Tags look like <tag>...</tag>
- Common tags: html, head, body, p, h<x> x={1,2,3}, title

## Activity: Simple HTML Page

- Open text editor (e.g., VSCode)
- Save document as .html
- Create example webpage below
- Open in web browser

```
1 <!DOCTYPE html>
2 <head>
3 <title>My First Webpage</title>
4 </head>
5 <body>
6 <h1>E155 Demo</h1>
7 Put text here!
8 </body>
```

#### **Other HTML Elements**

- Other HTML elements
  - Form
    - $\circ$  Attributes
      - type submit
      - action where to send form data
      - $\circ$  value text on button
- Add form to webpage

1 <form action="action\_key">
2 <input type="submit" value="Send GET request">

3 </form>

# **ESP8266 Overview and Demo**

#### **Overview**

ESP-WROOM-02 carries ESP8266EX highly integrated Wi-Fi SoC solution to meet the continuous demands for efficient power usage, compact design and reliable performance in the industry.

With the complete and selfcontained Wi-Fi networking capabilities, it can perform as either a standalone application (WROOM module itself) or the slave to an MCU host which is the primary intention of the click board as a whole. So, this click board is applied to any microcontroller design as a Wi-Fi adaptor through UART interface (RX,TX lines on mikroBUS pin socket).

Notes	Pin			mikro" BUS		Pin	Notes
	NC	1	AN	PWM	16	NC	
HW Reset	RST	2	RST	INT	15	NC	
Chip enable (active high)	EN	3	CS	ТХ	14	тх	UARTO_TXD / Transmit end in UART download (program) mode
	NC	4	SCK	RX	13	RX	UARTO_RXD / Receive end in UART download (program) mode
	NC	5	MISO	SCL	12	NC	
	NC	6	MOSI	SDA	11	NC	
Power supply	+3.3V	7	3.3V	5V	10	NC	
Ground	GND	8	GND	GND	9	GND	Ground



#### **Overview**

The Adafruit HUZZAH ESP8266 breakout is what we designed to make working with this chip super easy and a lot of fun. We took a certified module with an onboard antenna, and plenty of pins, and soldered it onto our designed breakout PCBs. We added in: - Reset button, - User button that can also put the chip into bootloading mode, - Red LED you can blink, - Level shifting on the UART and reset pin, - 3.3V out, 500mA regulator (you'll want to assume the ESP8266 can draw up to - - 250mA so budget accordingly) - Two diode-protected power inputs (one for a USB cable, another for a battery)

SAL XX SH XX

Two parallel, breadboard-friendly breakouts on either side give you access to:

- 1 x Analog input (1.0V max)
- 9 x GPIO (3.3V logic), which can also be used for I2C or SPI
- 2 x UART pins
- 2 x 3-6V power inputs, reset, enable, LDO-disable, 3.3V output

https://cdn.sparkfun.com/datasheets/Wireless/WiFi/ESP8266ModuleV1.pdf

#### ESP8266 Webserver Code

- Polls for waiting for a client to send an HTTP request
- When a request has been received, parses the request to slice the request after the /REQ: tag.
- Send the tag to the MCU which then decides what to do with the information.
- Then the MCU sends the content of the webpage back to the ESP8266 over the UART as properly formatted HTML.

## ESP8266 Demo

#### Wireshark

		S 🔦 🔶 🔿	Capturing from Wi-Fi: en0	
http	p && ip.addr==192.168.1.40			<b>•</b> •
No.	Time - Source	Destination Proto	pcol Length Info	
4	35613 8501.487211 192.168.1.4	0 192.168.1.124 HTTP	P 73 Continuation	
4	35611 8501.417374 192.168.1.4	0 192.168.1.124 HTTP	2 126 Continuation	
4	35609 8501.342990 192.168.1.4	0 192.168.1.124 HTTP	2 124 Continuation	
4	35603 8501.2/1980 192.168.1.4	0 192.168.1.124 HITP	90 Continuation	
4	125500 9501 1/0022 102 168 1 /	0 192.100.1.124 HITP	2 Continuation	
4	135595 8501.013972 192.168.1.1	24 192.168.1.40 HTTP	452 GET /BE0=0EE2 HTTP/1.1	
4	435552 8498,421552 192,168,1,4	0 192,168,1,124 HTTP	73 Continuation	
4	135550 8498.352296 192.168.1.4	0 192.168.1.124 HTTP	2 126 Continuation	
4	435548 8498.283938 192.168.1.4	0 192.168.1.124 HTTP	2 124 Continuation	
4	435545 8498.206892 192.168.1.4	0 192.168.1.124 HTTP	90 Continuation	
4	35543 8498.140880 192.168.1.4	0 192.168.1.124 HTTP	P 72 Continuation	
Л	1255/1 8/08 078352 102 168 1 /	0 102 168 1 12/ HTTP	2 83 Continuation	
	Opgrade=Insecure-Requests: In Accept: text/html,application/ User-Agent: Mozilla/5.0 (Macir Referer: http://192.168.1.40/F	~\n /xhtml+xml,application, ntosh; Intel Mac OS X <sup>^</sup> <b>REQ=ON</b> ?\r\n	n/xml;q=0.9,*/*;q=0.8\r\n 10_15_7) AppleWebKit/605.1.15 (KHTML, like Gecko) Version/14.0 Safari/605.1.	15\r
0050	73 74 3a 20 31 39 32 2e 31	36 38 2e 31 2e 34 30	st: 192. 168.1.40	
060	0d 0a 43 6f 6e 6e 65 63 74	69 6f 6e 3a 20 6b 65	··Connec tion: ke	
1070 1080	65 2d 49 6e 73 65 63 75 72	0a 55 70 67 72 61 64 65 2d 52 65 71 75 65	ep-alive ··upgrad	
090	73 74 73 3a 20 31 0d 0a 41	63 63 65 70 74 3a 20	sts: 1·· Accept:	
0a0	74 65 78 74 2f 68 74 6d 6c	2c 61 70 70 6c 69 63	text/htm l,applic	
000	61 74 69 61 6e 21 78 68 74 61 70 70 6c 69 63 61 74 69	6d 6c 2b 78 6d 6c 2c 6f 6e 2f 78 6d 6c 3b	ation/xh tml+xml,	
0d0	71 3d 30 2e 39 2c 2a 2f 2a	3b 71 3d 30 2e 38 0d	a=0.9,*/*;a=0.8	
0.00	0a 55 73 65 72 2d 41 67 65	6e 74 3a 20 4d 6f 7a	·User-Ag ent: Moz	
000	69 6c 6c 61 2f 35 2e 30 20	28 4d 61 63 69 6e 74	illa/5.0 (Macint	
0f0	6f 73 60 3h 30 40 60 74 65		och, Int ol Moc O	
0f0 100 110	6f 73 68 3b 20 49 6e 74 65 53 20 58 20 31 30 5f 31 35	6C 20 4d 61 63 20 4t 5f 37 29 20 41 70 70	osh; Int el Mac O S X 10 1 5 7) App	
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0f0 100 110 120 130 140 150	6 f 73 68 3b 20 49 6e 74 65 53 20 58 20 31 30 5f 31 35 6c 65 57 65 62 4b 69 74 2f 35 20 28 4b 48 54 4d 4c 2c 65 63 6b 6f 29 20 56 65 72 2e 30 20 53 61 66 61 72 69	6c         20         4d         61         63         20         4T           5f         37         29         20         41         70         70           36         30         35         2e         31         2e         31           20         6c         69         6b         65         20         47           73         69         6f         6e         2f         31         34           21         36         30         35         2e         31         24	osh; Int el Mac 0 S X 10_1 5_7) App LewebKit /605.1.1 5 (KHTML , like G ecko) Ve rsion/14 .0 Safar i/605.1.	
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#### Wrapup

- UART is a serial interface without a shared clock. Saves a wire, but at the cost of much slower data rates due to sampling overhead.
- Webpages in HTML are served using HTTP sending text over a serial connection.