E151 Lecture 4 – Diodes in Circuits

Matthew Spencer

Harvey Mudd College

ENGR151

Disclaimer

These are note for Prof. Spencer to give the lecture, they were not intended as a reference for students. Students asked for them anyway, so I'm putting them up as a courtesy. Remember that they are not intended as a substitute for lecture.

Diodes – why are they exponential?

- 3 descriptions: Nonlinear element, 1 way current valve, exponential
- Why exponential & 1 way?
- What's breakdown?

– what is I–V?

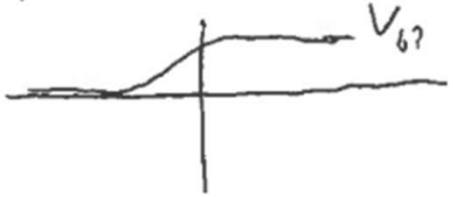
Reverse current – minority pushed across depl.

↳ push hard → $e^{-}/_{h^+}$ pairs, avalanche

↳ Fixed current ... limited by # carriers

Fwd current

– $\nabla V = E$



– E barrier is $\sim qV$

– Raise & lower w/ext. voltage

– Thermal $E = kT$

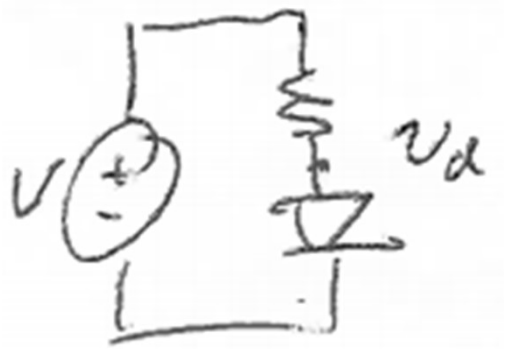
$\frac{V}{n\Phi_{TH}}$ ~ Thermal voltage ~26mV

$$I_D = I_S\left(e^{qV/nkT} - 1\right)$$

Probability of transit (let Vbi=0) – carrier limited drift

Can’t solve them gracefully

- Let’s make the easiest circuit: series resistor-diode ← transcendental
- Can’t even do easiest circuit! How to solve?
  - Graphically
  - Approximate
  - Linearize
  - Computers ← Don’t got straight here because we want design insight

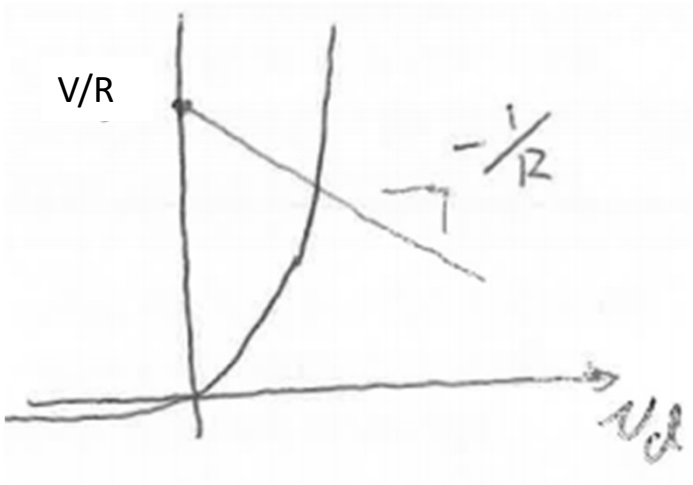


$$\frac{V - v_d}{R} = I_s\left(e^{v_d/n\phi_{th}} - 1\right)$$

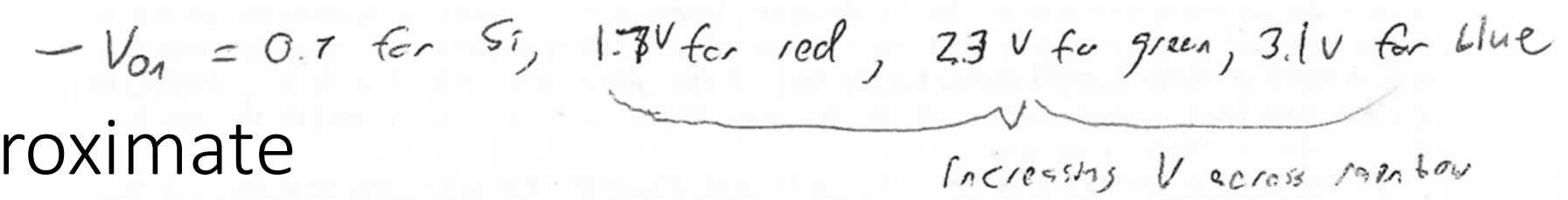
$$V = v_d + R I_s\left(e^{v_d/n\phi_{th}} - 1\right)$$

Graphically

- One point – “Operating point” or “Bias point” – where both eqn true
- This is called load line analysis
- Good for qualitative understanding, esp. with resistive loads

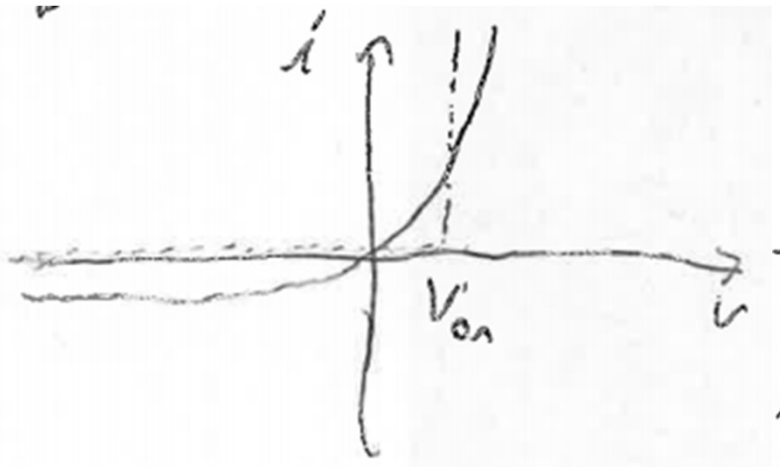


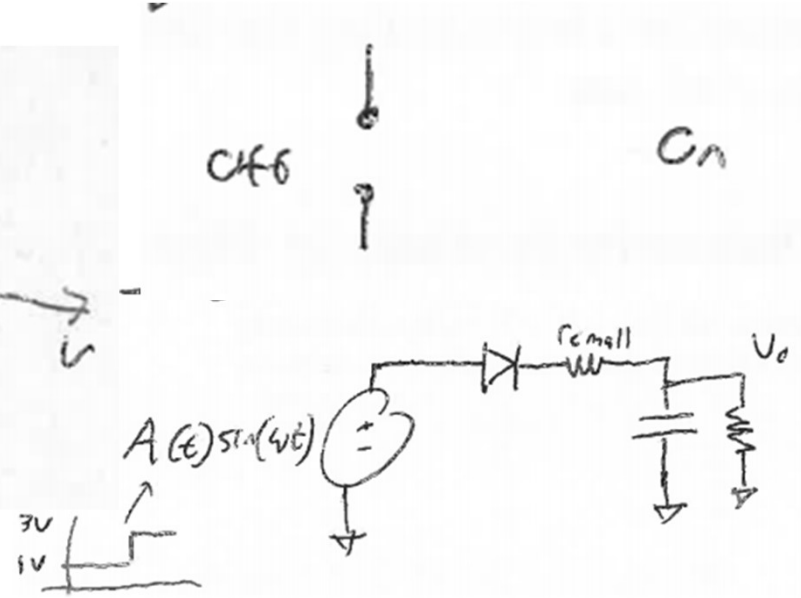
$$i = I_s\left(e^{v_d/nV_T} - 1\right) \quad \text{and} \quad i = \frac{V - v_d}{R}$$

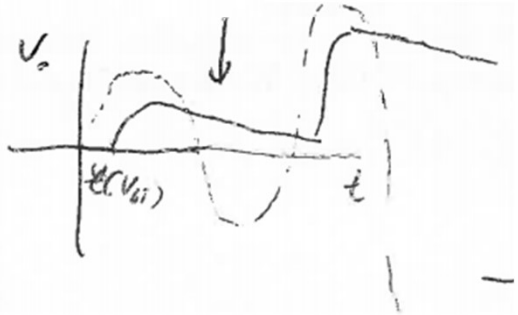


Approximate

- Exponential can be approximated by L shape: “inf current @ V_ON”
- (Only really works @ one current level, grain of salt)
- Switch-voltage source or switch–resistor model

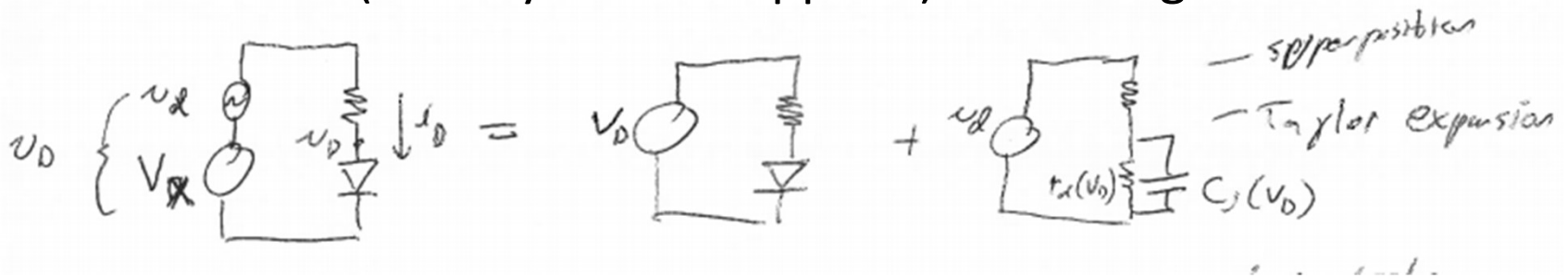


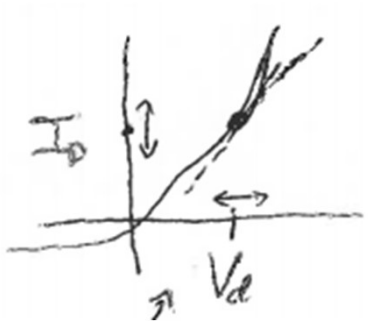




Linearize → Small signal modeling

- Time varying nonlinear hard in general: Is*exp(qV/nkT*sin(w*t) …)
- So do linear DC (already done in approx.) + small signal linear AC





$$f(x) \text{ near } a \simeq f(a) + \left.\frac{df}{dx}\right|_a \cdot (x-a) + \left.\frac{d^2 f}{dx^2}\right|_a \frac{(x-a)^2}{2} \cdots$$

$$i_d(v_D) \text{ near } V_D \simeq i_d(V_D) + \left.\frac{di_D}{dv_D}\right|_{V_D} \cdot v_d + \cdots$$

$i_d(V_D) = I_D$

$\left.\frac{di_D}{dv_D}\right|_{V_D}$: variation from V_D

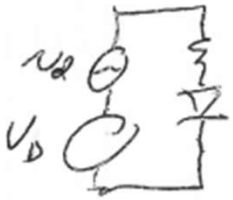
Differential Resistance

$$\frac{d i_D}{d v_D} = \frac{d}{d v_D} I_S\left(e^{v_D/n\phi_{th}} - 1\right) = \frac{1}{n\phi_{th}} I_S e^{v_D/n\phi_{TH}} \approx \frac{I_D}{n\phi_{th}}$$

- Define this as 1/rd ← differential resistance: rd = n*phi_th/I_D
- Eq. circuit is a resistor – voltage wiggle → linear I wiggle
- Notation: i_D (total signal) = I_D (large signal + i_d (small signal
- Need to shut off voltage sources b/c differential – “wiggles go to die”

If time:

example

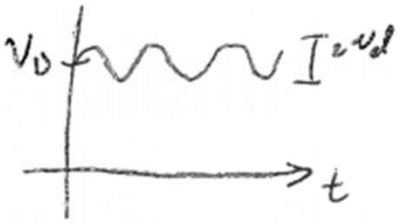


$$I_D = \frac{V_R - V_{on}}{R}$$

$$V_D = V_{on}$$

$$i_d \triangleq \frac{v_x}{R + n\phi_{th}/I_D}$$

$$v_{od} = \frac{n\phi_{th}/I_D}{R + n\phi_{th}/I_D} v_x$$



Computers

- Newton's method / iteration – TI-83+, Matlab, etc.
- Brute force – calculate every vd value and pick one that matches KCL
- Circuit simulator
  - LTSpice demo
  - Components and models
  - Simulator directives
  - "You may consider this like a calculator in this class, use it throughout"
  - AC vs. DC (or .OP) vs. TRAN