

## E11 Lecture 1: The Big Picture \& Digital Systems

Profs. David Money Harris \& Sarah Harris
Fall 2011

## Outline

Course Goals

- Syllabus
- From Zeroto One
- Boolean Logic
- Number Systems


## Course Goals

- Hands-on interdisciplinary introduction to what engineers and computer scientists do

Mechanical Engineering
Electrical Engineering
Computer Engineering
Computer Science
Design
Controls

## Course Goals (Part 2)

- Give students a tastes of what engineers and computer scientists do to help make informed major decisions Provide practical skills including:

Machine shop
3D CAD and printing
Soldering
C programming
Sensors \& actuators
Analog \& digital interfacing
Modeling
Embedded control systems

## Course Goals (Part 3)

Whet students' appetite to learn more advanced topics

- Develop skills:

Design - build - test - debug
Teamwork
Presentations
Technical writing
Just plain fun!

www.clker.com

## The Teaching Team

- Profs. David Money Harris \& Sarah Harris

Unusual course with a big component of peer teaching Three upper-class lab section instructors:
O Eric Zhang

- Greg Fong
- Brad Perfect \& Katie Vinnedge

Six sophomore lab assistants who took the course Fall 10

- Becca Thomas \& Vijay Ramakrishnan
- Tyler Robinson
- Alistair Dobke
- Stephen Pinto

Tutors

- Jeremy Usatine \& Josh Vasquez


## Schedule

| Week | Tue | Thurs | Lab | Problem Set (Due Tuesdays in class) |
| :--- | :--- | :--- | :--- | :--- |
| $0: 8 / 29$ | Big Picture, Digital Systems | C Programming I | 0: Shop safety briefing |  |
| $1: 9 / 5$ | Arduino Board | C Programming II | 1:Arduino Board |  |
| $2: 9 / 12$ | Design Representation | C Programmin III | 2:3D CAD \& Printing | Programming 1: Welcome to Arduino |
| $3: 9 / 19$ | Gold Codes | C Programming IV | 3: Machine Shop | Programming 2: Music \& Memory Game |
| $4: 9 / 26$ | Analog Circuits | Analog Circuit Analysis | 4: Robot Assembly | Programming 3: Gold Code Generation |
| $5: 10 / 3$ | Diodes \& Transistors | DEs, Capacitors \& Inductors | 5: Motors \& Sensors | Hardware 4: Volts \& Amps \& Ohms, Oh My! |
| $6: 10 / 10$ | Feedback Control | Motors | 6: Line-Following Robot | Programming 5: Reaction Timer \& Light Tag |
| $7: 10 / 17$ | Fall Break | Line Following Race | Break week: no lab |  |
| $8: 10 / 24$ | Game Kickoff; Team Dynamics | Mechanical Performance | Robot Design I | Programming 6: Gold Code Detection |
| $9: 10 / 31$ | Robot Navigation | Debugging | Robot Design II | Hardware 7: $1^{\text {It Order Circuits \& Transistors }}$ |
| $10: 11 / 7$ | Scrimmage | Batteries | Robot Design III | Hardware 8: Motors |
| $11: 11 / 14$ | Guest Lecture | Robotics Show \& Tell | Robot Design IV |  |
| $12: 11 / 21$ | Capture the Flag Game <br> (5:30 pm in Galileo) | Thanksgiving: no class | No lab |  |
| $13: 11 / 28$ | Technical Writing | Presentation Skills | Technical Writing |  |
| $14: 12 / 5$ | Peer Editing | Engineering Outlook | Presentations | Project Report (due Thursday 12/8) |

## Grading

- Pass/fail. To Pass:

Regularly attend class and labs
Complete all but one of the weekly labs
Complete all but one of the homework assignments
Deploy an operational autonomous vehicle to play Capture the Flag
Make a presentation about the vehicle
Complete a final report documenting your vehicle

## Collaboration Policy

- Labs 1-5:

Done on your own
You are welcome consult your instructors and classmates

- Lab 6 \& Final Project:

Done with a partner

- Problem Sets:

Done on your own or with a partner
Both of you should be engaged in all aspects
OK to discuss with other students after making an effort yourself

## From Zero to One

We'll be building digital systems
Simple building blocks: 0 and 1

- o = FALSE
- 1 =TRUE

Robustly assemble them into complex systems
(Much more on this in E85 and CS60 and E155)

## Digital Abstraction

0 and 1 could be represented by any physical quantity voltage current position of a mass
electron spin
reflectivity
magnetic polarity
water flow

- Most of these properties are continuous
- Only consider a discrete subset of the values


## The Analytical Engine

- Designed by Charles Babbage from 1834-1871
- Considered to be the first digital computer
- Built from mechanical gears, where each gear represented a discrete value (0-9)
- Babbage died before completion



## High and Low Voltages

Most digital systems today use voltage to process 0 and 1
0 = low voltage
1 = high voltage

- Power supply voltage: VDD (or VCC)

Formerly 5 V standard
Decreased toward 3.3, 2.5, 1.8, 1.2, 1.0, ...
We'll use VDD $=5 \mathrm{~V}$
Ground = o V

## Logic Levels



## Bits \& Binary Numbers

A 0 or 1 represents one of two states
Hence, it is called a binary digit, or bit
N bits can represent one of $\square$ states
Write as binary numbers

$$
\begin{aligned}
& 000 . . .000=0 \\
& 111_{1} . .111=2^{N_{-1}}
\end{aligned}
$$

- Leftmost bit is called most significant bit (weight $=2^{\mathrm{N}-1}$ )
- Rightmost bit is called least significant bit (weight = 1)


## Number Systems

## Decimal Numbers



$$
5374_{10}=\underset{\substack{\text { five } \\ \text { thousands }}}{5 \times 0^{3}}+\underset{\substack{\text { three } \\ \text { hundreds }}}{3 \times 10^{2}}+\underset{\substack{\text { seven } \\ \text { tens }}}{7 \times 10^{1}}+\underset{\substack{\text { four } \\ \text { ones }}}{4 \times 10^{0}}
$$

Binary Numbers


$$
1101_{2}=\underset{\substack{\text { one } \\ \text { eight }}}{1 \times 2^{3}}+\underset{\text { one }}{\text { four }} \underset{\text { for }}{1 \times 2^{2}}+\underset{\substack{\text { no } \\ \text { two }}}{0 \times 2^{1}}+\underset{\text { one }}{1 \times 2^{0}}=13_{10}
$$

## Powers of 2



$$
\text { - } 2^{2}=\square
$$

$$
\text { - } 2^{3}=\square
$$

$$
\text { - } 2^{4}=\square
$$

$$
\text { - } 2^{5}=\square
$$

$$
\text { - } 2^{6}=\square
$$

$$
\text { - } 2^{7}=\square
$$

- $2^{8}=\square$
- $2^{9}=\square$
- $2^{10}=\square$
- $2^{11}=\square$
- $2^{12}=\square$
- $2^{13}=\square$
- $2^{14}=\square$
- $2^{15}=\square$


## More Powers of 2

$2^{10}=1$ kilo
$2^{20}=1$ mega
$2^{30}=1$ giga
$2^{40}=1$ tera
$2^{50}=1$ peta
$\approx 1000$ (1024)
$\approx 1$ million $(1,048,576)$
$\approx 1$ billion (1,073,741,824)
$\approx 1$ trillion
₹ 1 quadrillion

## Number Conversion

## Decimal to binary conversion:

Convert 10011 ${ }_{2}$ to decimal

Decimal to binary conversion:
Convert $47_{10}$ to binary

## Addition

Decimal
$11 \leftarrow$ carries
3734
$\begin{array}{r}3168 \\ \hline 8902\end{array}$
Binary

> | 11 |
| :---: |
| 1011 |
| $+\quad 0011$ |
| 1110 |

## Addition Examples



## Signed Numbers

- How could we represent negative numbers in binary? "Two's complement" number system
Most significant bit has a weight of $-2^{\mathrm{N}-1}$
- Examples: 5-bit two's complement numbers

$00011_{2}$ $10011_{2}$



## Boolean Logic

Digital systems operate on o's and 1's to produce more o's and 1 's

Called Boolean Logic

## Charles Boole 1815-1864

- Born to working class parents
- Taught himself mathematics and joined the faculty of Queen's College in Ireland.
- Wrote An Investigation of the Laws of Thought (1854)
- Introduced binary variables
- Introduced the three fundamental logic operations: AND, OR, and NOT.


Scanned at the American Institute of Physics

## NOT Gate

## NOT <br>  <br> $$
Y=\bar{A}
$$ <br> $$
\begin{array}{c|c} A & Y \\ \hline 0 & \square \\ 1 & \square \end{array}
$$

## AND Gate

## AND



\[

\]

## OR Gate

## OR



\[

\]

## XOR Gate

$$
\begin{aligned}
& \text { XOR } \\
& Y=A \oplus B \\
& \begin{array}{cc|c}
A & B & Y \\
\hline 0 & 0 & \square \\
0 & 1 & \square \\
1 & 0 & \square \\
1 & 1 & \square
\end{array}
\end{aligned}
$$

